

Transient Stability of Grid-Forming Inverters: Differences between Grid-Forming Inverters and Synchronous Generators?

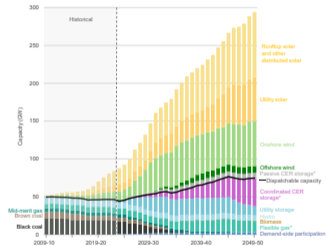
EPICS Workshop, CSIRO Energy Centre, Newcastle

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Renewable Energy Resources (RERs)

- Australia: 82% renewable electricity by 2030



Source: Australian Energy Market Operator (AEMO)

Energy Storage Systems (ESSs)

- Increasing deployment to support IBR integration



Source: 65 MW/130 MWh, Smithfield, NSW (Iberdrola Australia)

 RER &  ESS =  Inverter-Based Resources (IBRs)

I. Introduction to Grid-Forming Inverter and Transient Stability

II. Transient Dynamic Differences: Grid-Forming Inverters versus Synchronous Generators

III. Research Questions

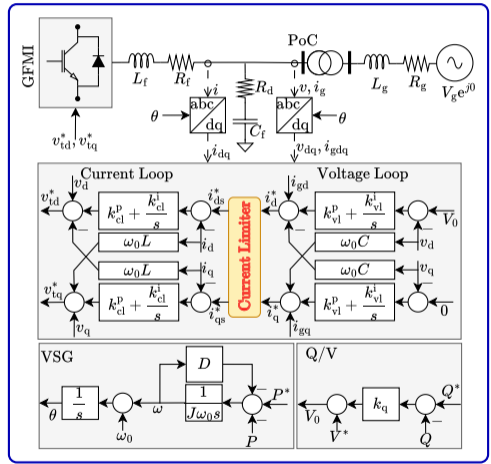
IV. Proposed Framework for GFMI Transient Stability

V. Future Work

Dual-Cascaded Control for GFMI

Dual-Cascaded Control for GFMI

- **Voltage control loop**
 - Regulates the PoC voltage
- **Current control loop**
 - Regulates the terminal current
- **Current Limiter**
 - Protection and fault-ride through



Dual-Cascaded Control

PoC: Point of Connection, GFMI: Grid-Forming Inverter

Fault Ride–Through and Transient Stability

- Fault Ride–Through: IBRs **stay connected** and **support the grid** under contingency events.

Grid Code	Typical Requirement
Fault tolerance capability	≥ 430 ms or until events are cleared
Dynamic voltage support	↑ LVRT: 4% of Rea. Cur. over 1% V ↓ HVRT: 6% of Rea. Cur. over 1% V
Fault-current capability	Maximum current capability
Sequence injection	• (+) seq. for symmetrical faults • (–) seq. for asymmetrical faults
Fast fault current support	Settle within 4 cycles

Chapter 5
Network Connection Access, Planning and Exp... > Chapter Schedule 5.2
Technical connection requirements for ge

SCHEDULE 5.2	Technical connection requirements for generating systems, integrated resource systems and synchronous condensers
CLAUSE S5.2.1	Application of the schedule
	(a) This schedule sets out details of additional requirements and conditions that a person to whom this schedule applies (described in paragraph (b)) must satisfy as a condition of connection to the power system of a production system or synchronous condenser system ("schedule 5.2 plant").

Australian NER (ver. 243)

IEEE SA
STANDARDS
ASSOCIATION

IEEE Standard for Interconnection and Interoperability of Inverter-Based Resources (IBRs) Interconnecting with Associated Transmission Electric Power Systems

IEEE Standard 2800-2022



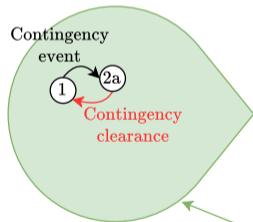
ARDS

Fault Ride-Through and Transient Stability

- **Transient Stability:** the ability to return to a desired stable equilibrium point after a **LARGE** contingency.

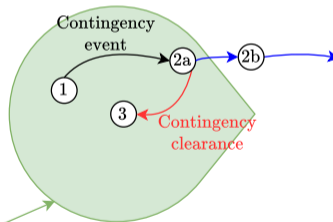
Small-signal stability

- Around **one equilibrium** point.
- **Linearized models**



Transient stability

- **All equilibrium** points.
- **Non-linear models.**



Stability margin = Region of Attraction

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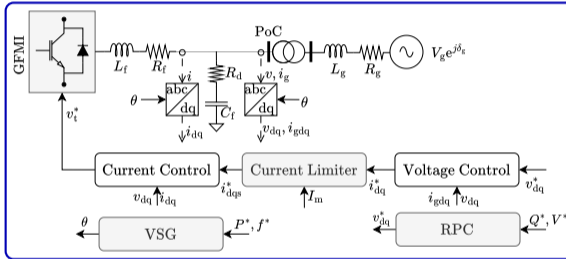
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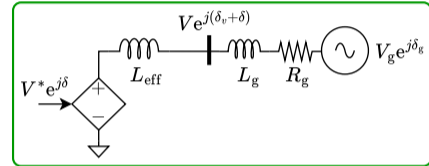
Impact of Current Limiters on Grid-Forming Inverter

Dual-Cascaded Control Architecture

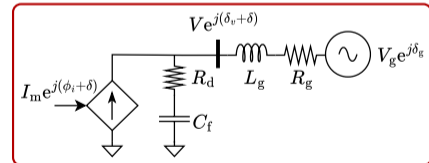


- Current limiter is inactive: a **voltage-source** mode.
- Current limiter is active: a **current-source** mode.

Current Limiter Inactive



Current Limiter Active



VSG: Virtual Synchronous Generator, RPC: Reactive Power Control

Challenges in GFMI Transient Stability Analysis

- ⚡ **Distinct dynamics:** GFMI_s behave differently from SG_s under FAULTS.
- ⚙️ **Modeling gap:** SG models cannot capture GFMI dynamics.
- 📊 **Analysis limitations:** Classical SG methods need major revision.

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1. ⚡ **Transient Dynamic Modeling:** GFMI under FAULTS.
2. 📊 **Quantification:** Effect on Stability Margin via White-box vs Black-box
3. 🏠 **Large-scale system:** GFMI Integration and Stability Margin

GFMI: Grid-Forming Inverter

I. Introduction to Grid-Forming Inverter and Transient Stability

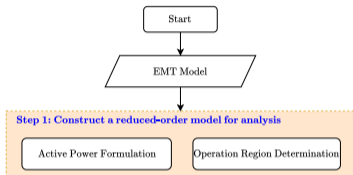
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Modeling for Transient Stability Analysis



Reduced-order model

$$\dot{\delta} = \omega_0 \omega,$$
$$J\omega_0 \dot{\omega} = -D\omega + P^* - P(\delta),$$

Active power characteristic

$$P(\delta) = \begin{cases} P_{\text{cum}}(\delta), & \text{current limiter active,} \\ P_{\text{clm}}(\delta), & \text{current limiter inactive,} \end{cases}$$

$$P_{\text{cum}}(\delta) = f(V_g, V^*, X_g, R_g, \delta),$$

$$P_{\text{clm}}(\delta) = g(V_g, I_m, X_g, R_g, \delta).$$

Equilibrium points

- **Stable equilibrium (SEP):**

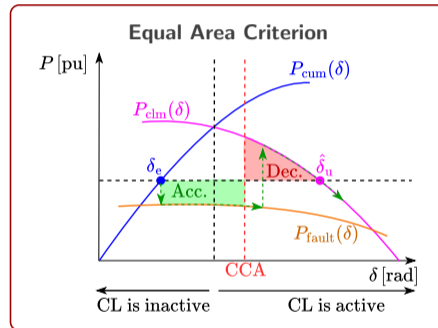
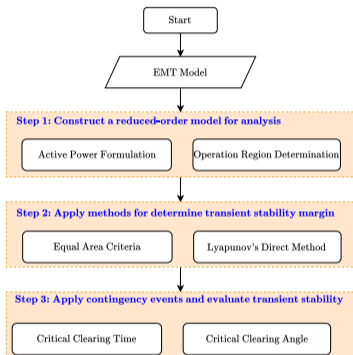
$$P_{\text{cum}}(\delta_e) = P^*$$

- **Unstable equilibrium (UEP):**

$$P_{\text{clm}}(\hat{\delta}_e) = P^*$$

EMT: Electromagnetic Transient

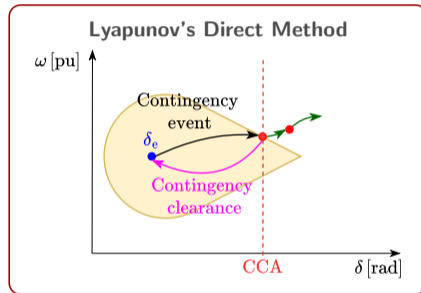
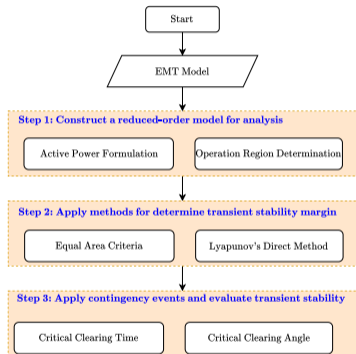
Estimation of Transient Stability Margin



- Neglects damping \rightarrow valid but conservative.
- Caution required when the current limiter is active.

EMT: Electromagnetic Transient

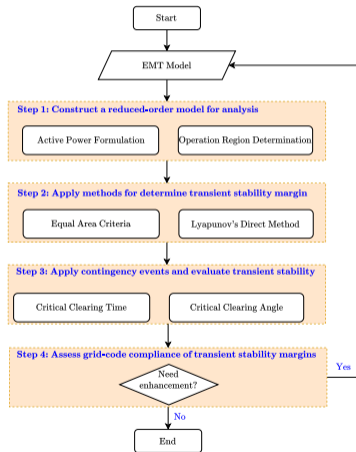
Estimation of Transient Stability Margin



- Hard to derive Lyapunov-based transient stability margin.
- Considering damping \rightarrow valid and less conservative.

EMT: Electromagnetic Transient

Grid-Code Check and Enhancement if Required



Grid-Code Check:

⚡ Tolerate fault up to (e.g., 430 ms)?

✔ Yes. Terminate process.

⚠ No. Let's enhance.

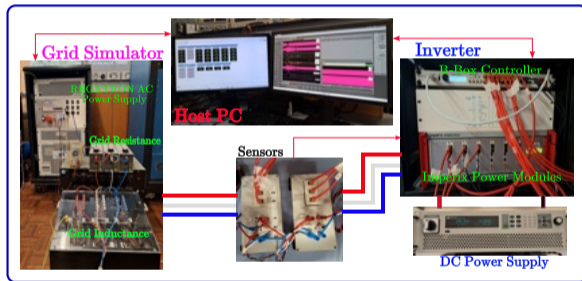
Enhancement methods:

- ✔ Adjust active power reference
- ✔ Temporarily increase inertia and damping
- ✔ Add virtual impedance/admittance
- ✔ Advanced strategies (e.g., *advanced current limiters*)

EMT: Electromagnetic Transient

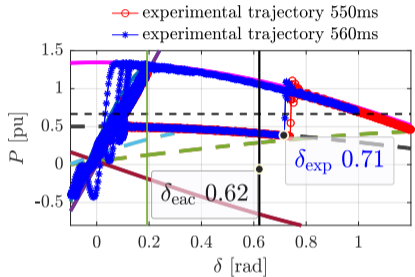
⚙️ Experimental Setup

- ⚡ Regatron AC.TCS: a grid voltage emulator.
- ⚡ Imperix Inverter (1.5 kVA, 110 V): a GFMI.
- ⚡ iTECH-500-40 DC Supply.
- ⚡ Impedance, sensors, and monitoring.



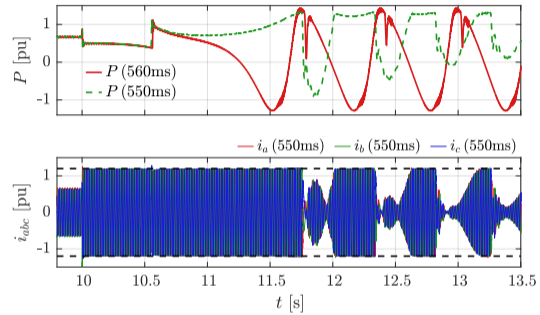
Experimental setup

Experimental Verification



Estimated Transient Stability Margin

- **Estimated** critical clearing angle: 0.62 rad
- **Experimental** critical clearing angle: 0.71 rad
- Estimation **error**: 13%



Experimental Response (SCR = 6.3)

SCR: Short Circuit Ratio

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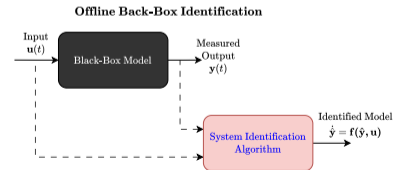
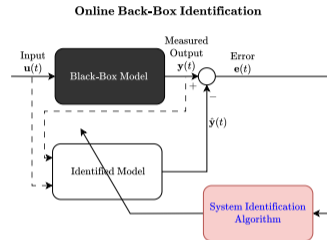
Transient Stability Assessment using Black-Box Models

⚠ Problem

- Tools rely on **white-box** models
- OEM-only access
- **Small-signal**: impedance scan
- **Transient stability**: ???

⚡ Solution

- **Non-linear Black-box identification**:
 - Extended Kalman Filter
 - Neural Network-based identification
- **Verification** via white-box methods:
 - Equal Area Criterion
 - Bifurcation theory





Thank you!

Q & A?