

Map deconstruction helps model construction

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Where available, the best predictor for the 3D geology of the subsurface is often the information contained in a geological map. This information falls into three categories of geometric data: positional data such as the position of faults, intrusive and stratigraphic contacts; topological data, such as the age relationships of faults and stratigraphic units, and gradient data, such as the dips of contacts or faults. In a 3D workflow, we combine all of these direct observations with conceptual information, including assumptions regarding the subsurface extent of faults and plutons to provide sufficient constraints to build a 3D geological model. Typically these conceptual assumptions are communicated via geological cross-sections supplied with the map, however these are often based on limited or no data. In the Loop Consortium we are developing algorithms that allow us to automatically deconstruct a geological map to recover the necessary positional, topological and gradient data as inputs to different 3D geological modelling codes. This automation provides significant advantages: it significantly reduces the time to first prototype models; it clearly separates the primary data from the data reduction steps and conceptual constraints; and provides a homogenous pathway to sensitivity analysis, uncertainty quantification and Value of Information studies.

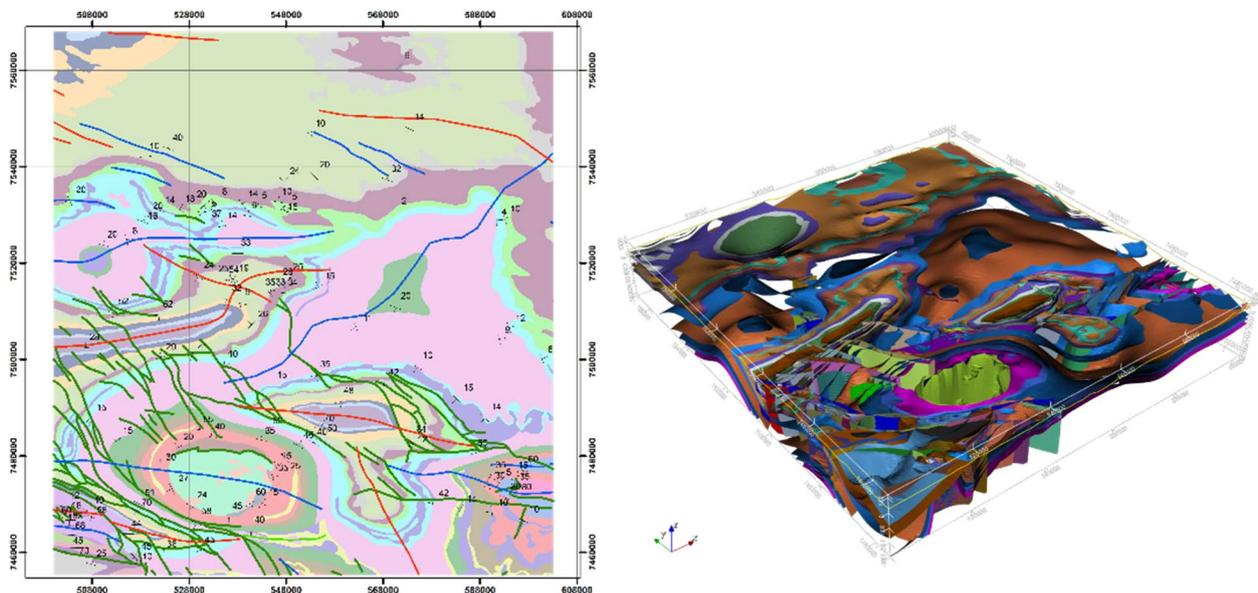


Figure 1. Left: Extract of the GSWA 500K Interpreted Bedrock Geology of the Mount Bruce area, Western Australia. Right: 3D Model built using only the information automatically extracted from the map.

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